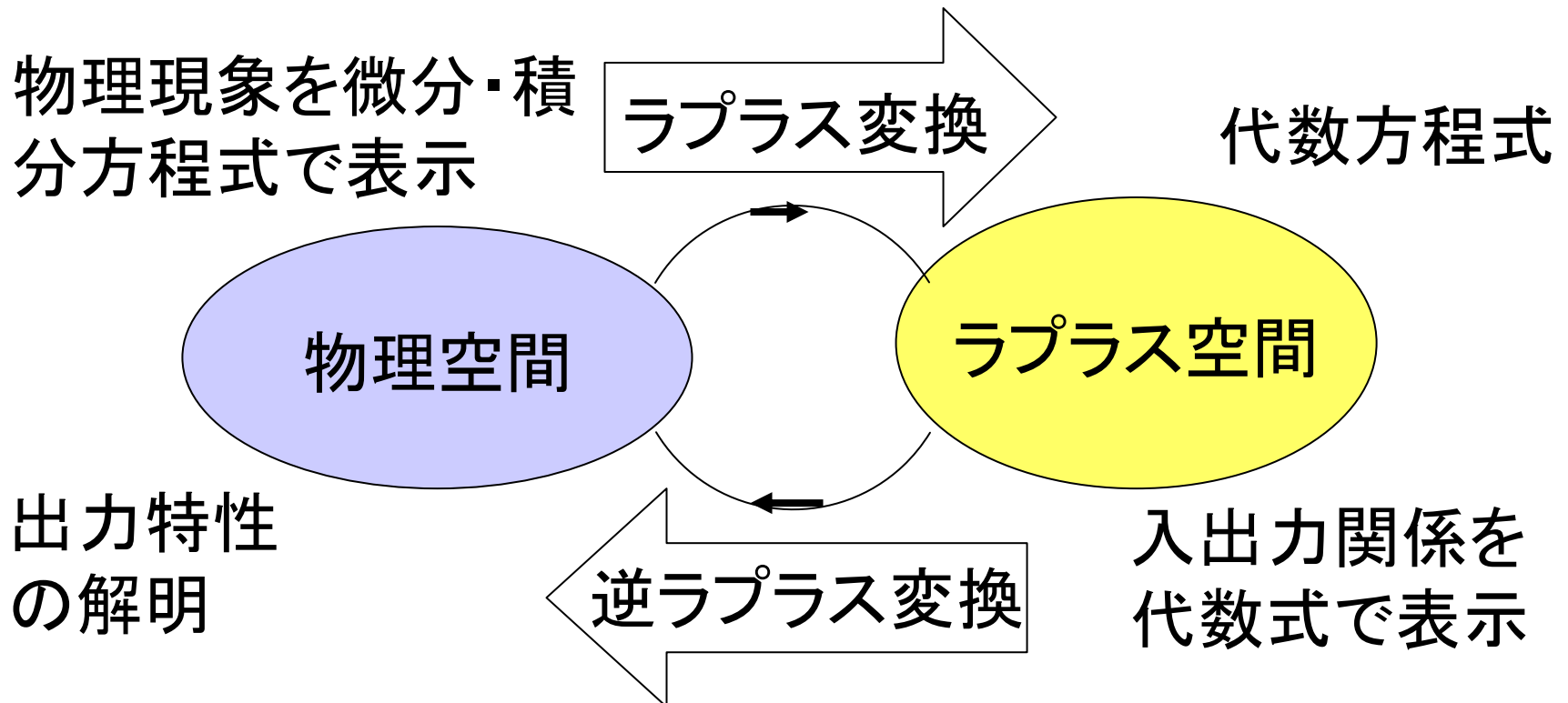


ラプラス変換 (Laplace transformation)

ラプラス変換 :
$$\mathcal{L}\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt = F(s)$$

逆ラプラス変換 :
$$\mathcal{L}^{-1}\{F(s)\} = \frac{1}{2\pi i} \int_{a-i\infty}^{a+i\infty} F(s) e^{st} ds = f(t)$$



[定理]

$$(1) \mathcal{L}\{f'(t)\} = sF(s) - f(0)$$

$$\mathcal{L}\left\{\frac{d^k f}{dt^k}\right\} = s^k F(s) - [s^{k-1} f(0) + \dots + f^{(k-1)}(0)]$$

$$(2) \mathcal{L}\left\{\int_a^t f(t) dt\right\} = \frac{1}{s} F(s) + \frac{1}{s} \int_a^0 f(t) dt$$

$$(3) \mathcal{L}\{e^{-at} f(t)\} = F(s)_{s \rightarrow s+a}$$

$$(4) \mathcal{L}\{f(t)u(t-a)\} = e^{-as} \mathcal{L}\{f(t+a)\}; \quad u(t): \text{step function}$$

$$(5) \lim_{s \rightarrow \infty} sF(s) = \lim_{t \rightarrow 0} f(t) = f(0)$$

$$(6) \lim_{s \rightarrow 0} sF(s) = \lim_{t \rightarrow \infty} f(t)$$

[公式]

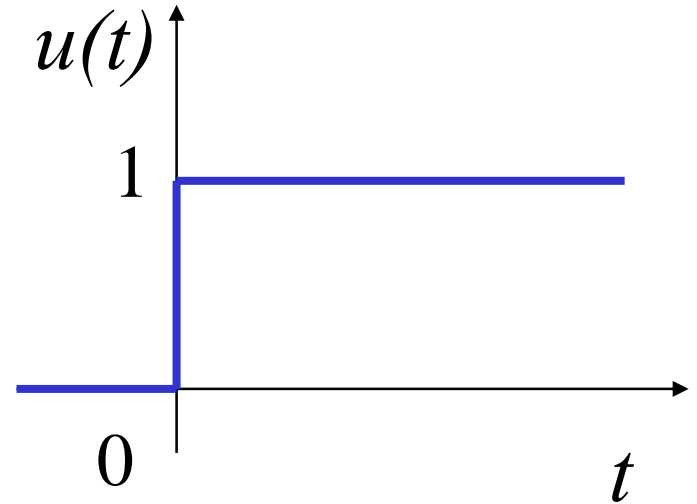
$$(1) \mathcal{L}\{u(t)\} = \frac{1}{s};$$

$u(t)$: step function

$$(2) \mathcal{L}\{e^{-at}\} = \frac{1}{s+a}$$

$$(3) \mathcal{L}\{t^k\} = \frac{k!}{s^{k+1}}; \quad k : \text{integer}$$

$$\sin bt = \frac{e^{ibt} - e^{-ibt}}{2i}, \quad \cos bt = \frac{e^{ibt} + e^{-ibt}}{2}$$



(物理系の例)

支配方程式: $a_2 x_o'' + a_1 x_o' + a_0 x_o = b_0 X_i e^{st}$

入力: $x_i = X_i e^{st}$ 出力: $x_o = X_o e^{st}$

ラプラス変換

$$X_o(s) = \left(\frac{b_o}{a_2 s^2 + a_1 s + a_o} \right) X_i = G(s) X_i$$

逆ラプラス変換

$$x_o(t) = X_o(s) e^{st} = G(s) X_i e^{st}$$

逆ラプラス変換

$$X(s) = \frac{s+a}{(s+b)^n} = \sum_{k=1}^n \frac{C_k}{(s+b)^k}$$

$$C_k = \lim_{s \rightarrow -b} \left[\frac{1}{k!} \frac{d^k}{ds^k} \left\{ (s+b)^n X(s) \right\} \right]$$

例

$$\begin{aligned} X(s) &= \frac{s+a}{s(s+b)^2(s+c)} \\ &= \frac{C_1}{s} + \frac{C_2}{(s+b)^2} + \frac{C_3}{s+b} + \frac{C_4}{s+c} \end{aligned}$$

$$C_1 = \lim_{s \rightarrow 0} [sX(s)] = \frac{a}{b^2 c}$$

$$C_4 = \lim_{s \rightarrow -c} [(s + c)X(s)] = \frac{a - c}{-c(b - c)^2}$$

$$C_2 = \lim_{s \rightarrow -c} [(s + b)^2 X(s)] = \frac{a - b}{-b(c - b)}$$

$$C_3 = \lim_{s \rightarrow -c} \left[\frac{d}{ds} \left\{ (s + b)^2 X(s) \right\} \right] = \frac{b^2 - 2ab + ac}{-b^2(c - b)^2}$$

$$x(t) = L^{-1} \{X(s)\} = C_1 + C_2 t e^{-bt} + C_3 e^{-bt} + C_4 e^{-ct}$$